Amendment to the Claims:

1. (Currently Amended) A method for controlling a drive motor [[(20)]] of a positive displacement vacuum pump [[(16)]], the method comprising the following steps:

storing a curve [[(32)]] indicating a respective speed n of the drive motor [[(20)]] for inlet pressure values p, wherein the curve [[(32)]] comprises comprising:

- [[-]] an upper range [[(34)]] for inlet pressure values p larger than or equal to an upper limit pressure p_1 , with a single constant upper speed value n_1 being associated with said upper range [[(34)]], and
- [[-]] an alteration range [[(36)]] for inlet pressure values p smaller than the upper limit pressure p_1 , wherein in the alteration range different speed values n_v are being associated with the inlet pressure values p[[,]];

determining the inlet pressure value p[[,]];

determining the speed n associated with the <u>determined</u> inlet pressure value p in the curve; [[(32),]] and

operating the drive motor [[(20)]] at the determined speed n.

- 2. (Currently Amended) The method according to claim 1, eharacterized in that wherein the curve [[(32)]] comprises a lower range [[(38)]] for inlet pressure values p smaller than or equal to a lower limit pressure p₂, a single constant lower speed value n₂ [[is]] being associated with the lower range [[(38)]], and the alteration range [[(36) is]] being limited to inlet pressure values p larger than the lower limit pressure p₂.
- 3. (Currently Amended) A method for controlling a drive motor [[(20)]] of a positive displacement vacuum pump [[(16)]], the method comprising the following steps:

storing a curve [[(32)]] indicating a respective speed n of the drive motor [[(20)]] for inlet pressure values p, wherein the curve [[(32)]] comprises comprising:

- [[-]] a lower range [[(38)]] for inlet pressure values p smaller than or equal to a lower limit pressure p_2 , with a single constant lower speed value n_2 being associated with said lower range [[(38)]],
- [[-]] an alteration range [[(36)]] for inlet pressure values p larger than the lower limit pressure p_2 , wherein in the alteration range [[(36)]] different speed values n_v are being associated with the inlet pressure values p[[,]]:

determining the inlet pressure value p[[,]];

determining the speed n associated with the <u>determined</u> inlet pressure value p in the curve; [[(32),]] and

operating the drive motor [[(20)]] at the determined speed n.

- 4. (Currently Amended) The method according to any one of elaims claim 1[[-3]], eharacterized in that wherein in the alteration range [[(36)]] decreasing speeds n_v are associated with decreasing inlet pressure values p.
- 5. (Currently Amended) The method according to any one of elaims claim 2[[1-4]], characterized in that wherein the upper limit value p_1 ranges between 20 mbar and 1 mbar, and the lower limit value p_2 ranges between 1.0 mbar and 0.005 mbar.
- 6. (Currently Amended) The method according to any one of elaims claim 2[[1-4]], eharacterized in that wherein the upper constant speed value n_1 ranges between 2,200 and 1,000 rpm, and the lower constant speed value n_2 ranges between 300 and 1,300 rpm.
- 7. (Currently Amended) The method according to any one of elaims claim 1[[-6]], eharacterized in that wherein the positive displacement vacuum

pump [[(16)]] is a fore vacuum pump arranged upstream of a high vacuum pump [[(14)]], and the inlet pressure p is the \underline{a} suction-side pressure of the high vacuum pump [[(14)]].

- 8. (Currently Amended) The method according to any one of elaims claim 1[[-7]], eharacterized in that wherein the curve [[(32)]] is saved in a characteristic diagram storage.
- 9. (Currently Amended) The method according to any one of elaims claim 1[[-8]], eharacterized in that wherein the drive motor [[(20)]] is an asynchronous motor.
- 10. (Currently Amended) A positive displacement vacuum pump [[(16)]] comprising:

a drive motor [[(20)]], an inlet pressure sensor [[(24)]] and a drive motor control [[(22)]] for controlling the <u>a</u> speed n of the drive motor [[(20)]] in dependence on the inlet pressure value p determined by the inlet pressure sensor [[(24)]],

wherein—the drive motor control [[(22)]] comprises comprising a storage for storing a curve [[(32)]] which indicates a respective speed n of the drive motor [[(20)]] for inlet pressure values p of the inlet pressure sensor [[(24)]], wherein the curve [[(32)]] comprises comprising:

at least one of (a)an upper range [[(34)]] for inlet pressure values p larger than or equal to an upper limit pressure p₁, with a single constant upper speed value n₁ being associated with said upper range and (b) a lower range for the inlet pressure values p lower than or equal to a lower pressure limit p_s, a single constant lower speed value n₂ being associated with the lower range; [[(34),]] and

[[-]] an alteration range [[(36)]] for inlet pressure values p smaller than the upper limit pressure p_1 or larger than the lower limit pressure p_s , wherein in the alteration range [[(36)]]

different speed values n_v are being associated with the inlet pressure values p.

- 11. (Currently Amended) The positive displacement vacuum pump according to claim 10, characterized in that wherein the drive motor control [[(22)]] comprises a processor [[(28)]] which has connected therewith the inlet pressure sensor [[(24)]] and which evaluates the signals of from the inlet pressure sensor [[(24)]].
- 12. (New) The method according to claim 3, wherein in the alteration range decreasing speeds n_v are associated with decreasing inlet pressure values p.
- 13. (New) The method according to claim 3, wherein the positive displacement vacuum pump is a fore vacuum pump arranged upstream of a high vacuum pump, and the inlet pressure p is a suction-side pressure of the high vacuum pump.
- 14. (New) The method according to claim 3, wherein the curve is saved in a characteristic diagram storage.
- 15. (New) The method according to claim 3, wherein the drive motor is an asynchronous motor.